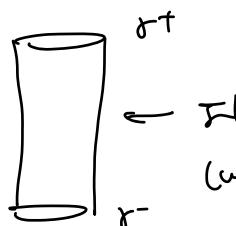


## Application of SFT

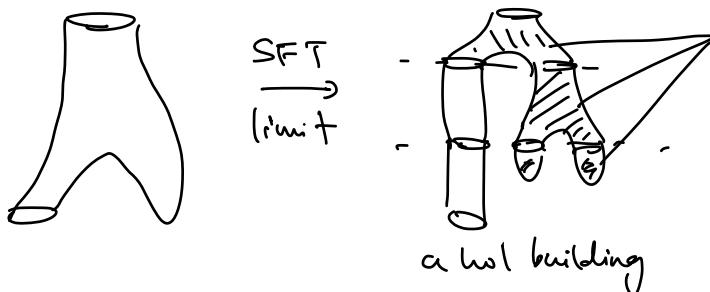
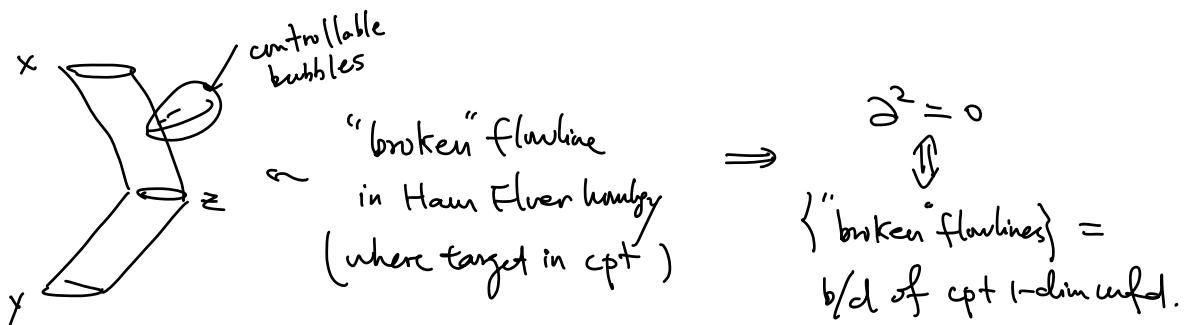
### 1. Cylindrical contact homology

Similarly to Ham Floer homology, given a contact mfld  $(M, \beta = ker \alpha)$  one can consider SM symplectization and a Floer theory based on closed Reeb orbits, connected by  $\mathbb{J}$ -hol cylinders



Question: define  $\partial$  and show  $\partial^2 = 0$ .

An obvious trouble:  $\partial^2 = 0$  involves counting index=2 cylinders and in particular "boundary" elements in compactification of moduli space.



These components are in general not in the top type of cylinders (due to SM is un-cpt).

Here is a quick way to fix this  $\rightarrow$  simply requiring there does not exist any contractible closed Reeb orbits.

Def. Fix a homotopy class  $h \in [S^1, M]$  and assume it is primitive (i.e. not iteration of another htp class).

Denote  $P_h(\alpha) = \{ \text{closed Reeb orbits of } (M, \xi = \ker \alpha) \text{ in class } h \}$

We call  $\alpha$  for contact str  $\xi$   $h$ -admissible if (1)  $\nexists$  any contractible closed Reeb orbit; (2) any element in  $P_h(\alpha)$  is unbdg.

$\xrightarrow{\text{to guarantee that limit behavior of } J\text{-hol/curve in } SM \text{ is "uniform"}}$

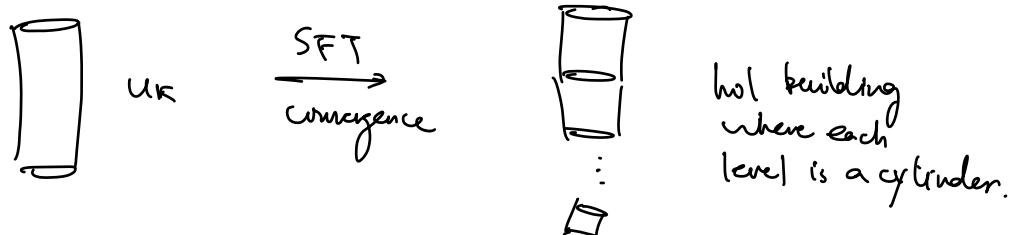
Rmk "h is primitive" is to make sure no multiple covering.

$\Rightarrow$  consider only hol cylinders between closed Reeb orbit (from  $P_h(\alpha)$ ) with one positive end and one negative end, then

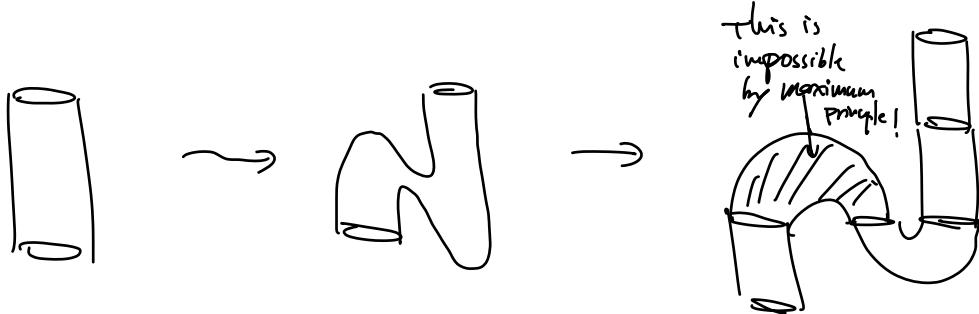
$\{ J \text{ a.c.s on } SM \mid \# J\text{-hol cylinder induces} \}$   
Fredholm operator

is generic (b/c no multiple cover  $\Leftrightarrow$  simple  $\Leftrightarrow$  <sup>somewhat</sup>  $\hookrightarrow$  injective).

No contractible closed Reeb orbits  $\Rightarrow$  a compactness result (Prop 10.19  
in [Wen])



e.g.



⇒ Under this  $h$ -admissible condition, we can use cylinders to form a fiber theory.

Define  $\mathbb{C}C_*^h(M, \alpha) := \bigoplus_{\gamma \in P_h(\alpha)} \mathbb{Z}_2 \langle \gamma \rangle$

← each admits a grading  $n-3 + M_{\gamma}^{\infty}(r)$   
 (depending on a choice of orientation)

$$\partial \gamma = \sum_{\gamma' \in P_h(\alpha)} \#_{\gamma} M^{\text{index}=1} \left( \square_{\gamma'}^{\gamma} \right) /_{\mathbb{R}} \cdot \gamma'$$

Here,  $\text{index} = \text{ind}(u)$  ( $\simeq$  difference of grading of  $\gamma$  and  $\gamma'$ )

(Note that a trivial cylinder  $\square_{\gamma}^{\gamma}$  is identified with a point after modulo  $\mathbb{R}$ -translation.)

Prop 1.1.21 ⇒ For a generic  $J$ , fixed  $\gamma^{\pm} \in P_h(\alpha)$ ,

$$\overline{M^{\text{ind}=\pm}(\square_{\gamma^{\pm}}^{\gamma^{\mp}})} = \text{cpt ind ind wfd with b/d}$$

and  $\partial \overline{M^{\text{ind}=\pm}(\square_{\gamma^{\pm}}^{\gamma^{\mp}})} = \bigsqcup_{\gamma_0 \in P_h(\alpha)} M^{\text{ind}=1}(\square_{\gamma_0}^{\gamma^{\mp}}) \times M^{\text{ind}=1}(\square_{\gamma_0}^{\gamma^{\pm}})$

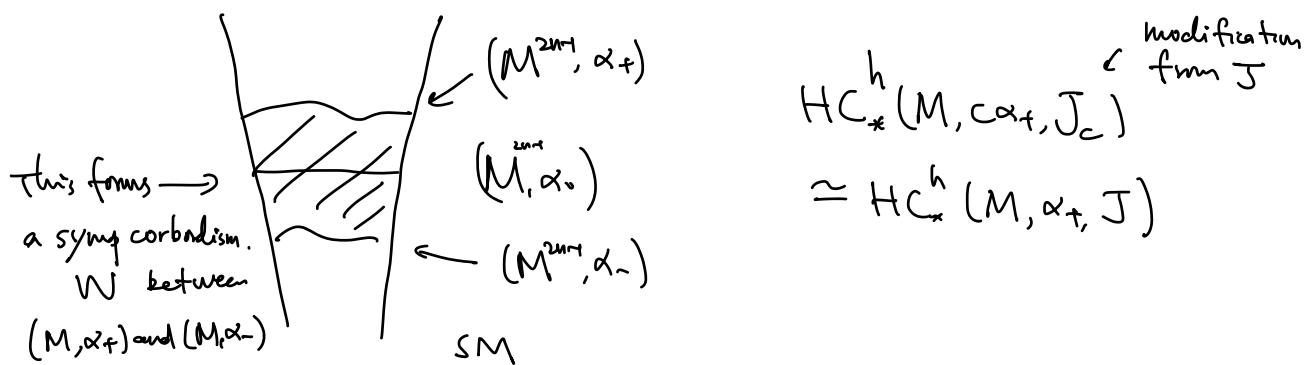
$$\Rightarrow \partial^2 = 0$$

$$\Rightarrow HC_*^h(M, \alpha, J) := H_*(CC_*^h(M, \alpha), \partial).$$

Question: Dependence on  $\alpha$  and  $J$ ?

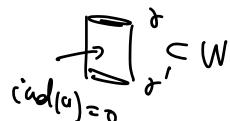
Given  $\alpha_+ =_{\text{fixed}} \alpha_-$  and  $J$   
 Given  $\alpha_+$  of  $\{, \wedge\}$  by rescaling  $\alpha_+$  by constant  $c \Rightarrow 1$ ,

assume  $f_+ > f_-$  pointwise:



Then consider  $\mathbb{E}_*^J : CC_*^h(M, \alpha_+) \rightarrow CC_*^h(M, \alpha_-)$

$$\partial \rightarrow \partial'$$



and verify that

$$\begin{array}{ccc}
 CC_*^h(M, \alpha_+) & \xrightarrow{\mathbb{E}_*^J} & CC_*^h(M, \alpha_-) \\
 \partial_+ \downarrow & \curvearrowright & \downarrow \partial_- \\
 CC_{*-1}^h(M, \alpha_+) & \xrightarrow{\mathbb{E}_{*-1}^J} & CC_{*-1}^h(M, \alpha_-)
 \end{array}$$

This diagram commutes, so  $\mathbb{E}_*^J$  is a chain map.

$$\Rightarrow \underline{\Xi}^J_* : HC_*^h(M, \alpha_+, J) \longrightarrow HC_*^h(M, \alpha_-, J)$$

a well-defined homomorphism.

any  $\alpha$

In a similar way, for  $J, J'$ ,  $\exists \underline{\Xi}^{J, J'}_* : HC_*^h(M, \alpha, J) \xrightarrow{\text{any } \alpha} HC_*^h(M, \alpha, J')$

$$\Rightarrow HC_*^h(M, \alpha_+, J) \xrightarrow{\underline{\Xi}^J_*} HC_*^h(M, \alpha_-, J) \xrightarrow{\underline{\Xi}^{J, J'}_*} HC_*^h(M, \alpha_-, J')$$

$\xrightarrow{\underline{\Xi}}$

Then switching  $(\alpha_+, J)$  and  $(\alpha_-, J')$ , we get  $\underline{\Xi}$  and verify

$$\underline{\Xi} \cdot \underline{\Xi} = \underline{\Xi} \cdot \underline{\Xi} = 1 \Leftarrow \text{counting trivial cylinders.}$$

$$\Rightarrow HC_*^h(M, \alpha, J) \underset{\text{def}}{=} HC_*^h(M, \{\}).$$

This is called the cylindrical contact homology  
of contact mfld  $(M, \{\})$ .

Prop:  $\varphi : (M, \{\}) \rightarrow (M', \{\})$  contactomorphism s.t.  $\varphi_* h = h'$

for  $h \in [S^1, M]$ . Assume  $\exists$  contact 1-form  $\alpha'$  of  $\{\}$  s.t.  $\alpha'$  is  $h'$ -admissible, then  $\exists$  contact 1-form  $\alpha$  of  $\{\}$  s.t.  $\alpha$  is  $h$ -admissible and  $HC_*^h(M, \{\}) = HC_*^{h'}(M', \{\})$ .

$\Rightarrow HC_*^h(M, \{\})$  defines a contact invariant (of contact str)<sub>up to contactomorphism</sub>.

One can use  $HC_*^h(M, \{\})$  to distinguish different contact str.

Ex:  $T^3 = S^1 \times S^1 \times S^1$ , where  $S^1 = \mathbb{R}/\mathbb{Z}$ , in coordinate  $(\rho, \varphi, \theta)$ .

Consider  $\alpha_k := \cos(2\pi k \rho) d\theta + \sin(2\pi k \rho) d\varphi$ .  $k \in \mathbb{N}_{\geq 1}$ .

$$\begin{aligned}
 \text{Then } \alpha_k \wedge d\alpha_k &= (\cos(2\pi k \rho) d\theta + \sin(2\pi k \rho) d\varphi) \wedge \\
 &\quad 2\pi k \rho (-\sin(2\pi k \rho) d\rho \wedge d\theta + \cos(2\pi k \rho) d\rho \wedge d\varphi) \\
 &= 2\pi k \rho (-\sin^2(2\pi k \rho) d\varphi \wedge d\rho \wedge d\theta + \\
 &\quad \cos^2(2\pi k \rho) d\theta \wedge d\rho \wedge d\varphi) \\
 &= 2\pi k \rho d\rho \wedge d\varphi \wedge d\theta > 0
 \end{aligned}$$

Reeb vector field  $R_{\alpha_k}$  is

$$R_{\alpha_k} = \sin(2\pi k \rho) \partial_\varphi + \cos(2\pi k \rho) \partial_\theta$$

$\Rightarrow$  closed Reeb orbits are in the form:

$$\begin{aligned}
 \{\rho\} \times \mathbb{T}^2 &\simeq \{\rho\} \times \text{Diagram} \\
 \left( \mathbb{T}^3 = \bigcup_{\rho \in \mathbb{N}/2} \{\rho\} \times \mathbb{T}^2 \right)
 \end{aligned}$$

In particular, all closed Reeb orbits are non-contractible.

Rmk These orbits are degenerate (so extra work is needed).

Thm For  $h = [t \mapsto (0, 0, t)]$ , we have

$$HC_*^h(\mathbb{T}^3, \{\rho\}_k) = \begin{cases} \mathbb{Z}_2^k & * \text{ is odd} \\ \mathbb{Z}_2 & * \text{ is even} \end{cases}$$

$\Rightarrow$  For different  $k, l$ ,  $\mathcal{S}_k \overset{\text{cont}}{\neq} \mathcal{S}_l$ .

(Here one needs to practice an exercise: if  $h, h' \in [S^1, \mathbb{P}^3]$ , primitive and mapped to trivial class under projection  $\mathbb{P}^3 \rightarrow S^1$ ,  $(p, \varphi, 0) \rightarrow p$ . Then  $\exists$  a contactomorphism  $\varphi: (\mathbb{P}^3, \mathcal{S}_k) \rightarrow S^1$  s.t.  $\varphi_* h = h'$ .)

Remark Observe that for each  $k \in \mathbb{N}_{\geq 1}$ , consider smooth deformations,

$$\ker((1-s)\alpha_k + s dp) \quad s \in [0, 1]$$

and we get from  $\mathcal{S}_k$  ( $= \ker \alpha_k$ ) to  $\ker(dp)$ . So topologically all hypersurfaces  $\mathcal{S}_k$  ( $\text{for } k \in \mathbb{N}_{\geq 1}$ ) are the same.

( $\Rightarrow$  we need refined contact geo machinery to distinguish  $\mathcal{S}_k, \mathcal{S}_l$ ).

Remark This result has been known since 90s (by Giroux, Kanda).