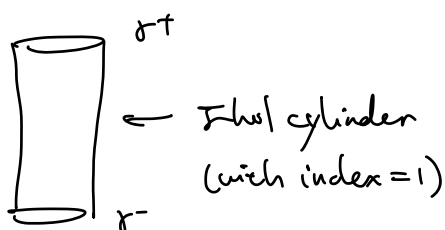


Application of SFT

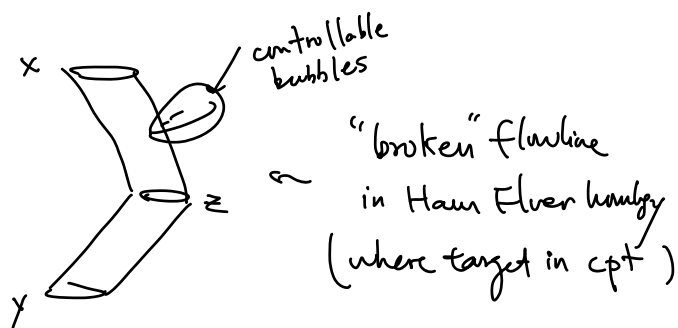
1. Cylindrical contact homology

Similarly to Ham Floer homology, given a contact mfd $(M, \xi = \ker \alpha)$ one can consider SM symplectization and a Floer theory based on closed Reeb orbits, connected by J-hol cylinders

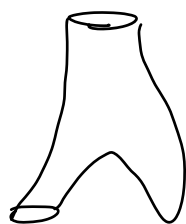


Question: define ∂ and show $\partial^2 = 0$.

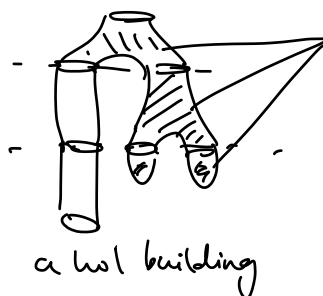
An obvious trouble: $\partial^2 = 0$ involves counting index=2 cylinders and in particular "boundary" elements in compactification of moduli space



$$\begin{aligned} \partial^2 &= 0 \\ \iff \\ \{\text{"broken flowlines"}\} &= \text{b/d of cpt 1-dim mfd.} \end{aligned}$$



SFT
→
limit



These components are in general not in the top type of cylinders (due to SM is non-cpt).

Here is a quick way to fix this \rightarrow simply requiring there does NOT exist any contractible closed Reeb orbits.

Def. Fix a homotopy class $h \in [S', M]$ and assume it is primitive (i.e. not iteration of another htp class).

Denote $P_h(\alpha) = \{ \text{closed Reeb orbits of } (M, \omega_{ker \alpha}) \text{ in class } h \}$

We call α for contact str $\{ \}$ h -admissible if (1) \nexists any contractible closed Reeb orbit; (2) any element in $P_h(\alpha)$ is non-deg.

\rightarrow to guarantee that limit behavior of J-hol curve in SM is "uniform".

Rmk " h is primitive" is to make sure no multiple covering.

\Rightarrow consider only hol cylinders between closed Reeb orbit (from $P_h(\alpha)$) with one positive end and one negative end, then

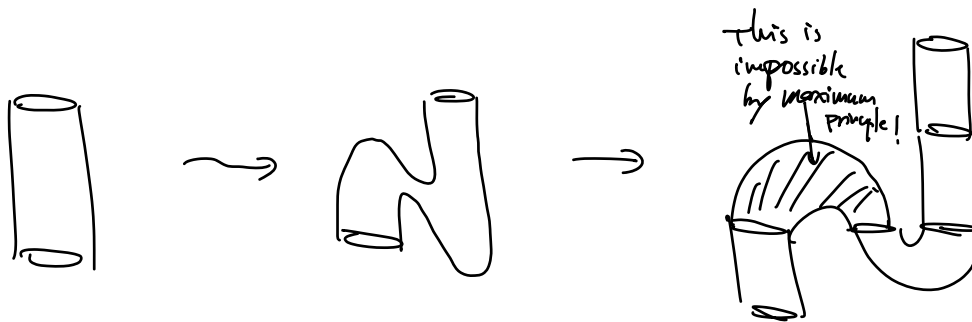
$\{ J \text{ a.c.s on SM } \mid \nexists J\text{-hol cylinder induces Fredholm operator} \}$

is generic (b/c no multiple cover \Leftrightarrow simple \Leftrightarrow somewhere injective).

No contractible closed Reeb orbits \Rightarrow a compactness result (Prop 10.19 in [LW03])



e.g.



\Rightarrow Under this h -admissible condition, we can use cylinders to form a Floer theory.

Define $CC_*^h(M, \alpha) := \bigoplus_{\gamma \in P_h(\alpha)} \mathbb{Z}_2 \langle \gamma \rangle$ \leftarrow each admits a grading $n-3+M_{\mathbb{R}}^{\mathbb{Z}}(\gamma) \in \mathbb{Z}$ (depending on choice of trivialization)

$$\partial \gamma = \sum_{\gamma' \in P_h(\alpha)} \#_{\mathbb{Z}_2} M^{\text{index}=1} \left(\boxed{u}_{\gamma'}^{\gamma} \right) / \mathbb{R} \cdot \gamma'$$

Here, $\text{index} = \text{ind}(u)$ (= difference of grading of γ and γ')

(Note that a trivial cylinder $\boxed{u}_{\gamma}^{\gamma}$ is identified with a point after modulo \mathbb{R} -translation.)

Prop 10.21 \Rightarrow For a generic J , fixed $\gamma^{\pm} \in P_h(\alpha)$,

$$\overline{M^{\text{ind}=2} \left(\boxed{u}_{\gamma^-}^{\gamma^+} \right)} = \text{cpt indim wfd with } b/d$$

$$\text{and } \partial \overline{M^{\text{ind}=2} \left(\boxed{u}_{\gamma^-}^{\gamma^+} \right)} = \bigsqcup_{\gamma_0 \in P_h(\alpha)} M^{\text{ind}=1} \left(\boxed{u}_{\gamma_0}^{\gamma^+} \right) \times M^{\text{ind}=1} \left(\boxed{u}_{\gamma^-}^{\gamma_0} \right).$$

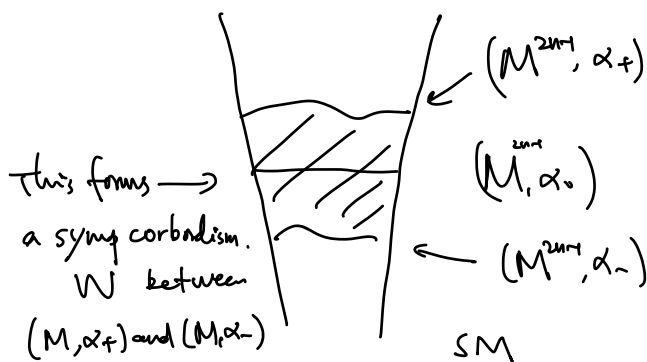
$$\Rightarrow \partial^2 = 0$$

$$\Rightarrow HC_*^h(M, \alpha, J) := H_*(CC_*^h(M, \alpha), \partial).$$

Question: Dependence on α and J ?

Given $\alpha_{\pm} = f_{\pm} \alpha_0$ and J
 of $\{, \wedge\}$ by rescaling α_+ by constant $c \gg 1$,

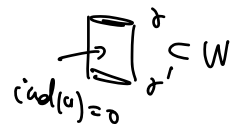
assume $f_+ > f_-$ pointwise:



$$HC_*^h(M, c\alpha_+, J_c) \xleftarrow{\text{modification from } J} \cong HC_*^h(M, \alpha_+, J)$$

$$\text{Then consider } \Phi_*^J: CC_*^h(M, \alpha_+) \rightarrow CC_*^h(M, \alpha_-)$$

$$\sigma \rightarrow \sigma'$$



and verify that

$$\begin{array}{ccc} CC_*^h(M, \alpha_+) & \xrightarrow{\Phi_*^J} & CC_*^h(M, \alpha_-) \\ \partial_+ \downarrow & \curvearrowright & \downarrow \partial_- \\ CC_{*+1}^h(M, \alpha_+) & \xrightarrow{\Phi_{*+1}^J} & CC_{*+1}^h(M, \alpha_-) \end{array}$$

this diagram commutes, so Φ_*^J is a chain map.

$$\Rightarrow \Phi_*^J : HC_*^h(M, \alpha_+, J) \longrightarrow HC_*^h(M, \alpha_-, J)$$

a well-defined homomorphism.

In a similar way, for $J, J', \exists \Phi_*^{J, J'} : HC_*^h(M, \alpha, J) \xrightarrow{\text{any } \alpha} HC_*^h(M, \alpha, J')$

$$\Rightarrow HC_*^h(M, \alpha_+, J) \xrightarrow{\Phi_*^J} HC_*^h(M, \alpha_-, J) \xrightarrow{\Phi_*^{J, J'}} HC_*^h(M, \alpha_-, J')$$

$\xrightarrow{\Phi}$

Then switching (α_+, J) and (α_-, J') , we get Φ and verify

$$\Phi \circ \Phi = \Phi \circ \Phi = 1 \leftarrow \text{counting trivial cylinders.}$$

$$\Rightarrow HC_*^h(M, \alpha, J) \xrightarrow{\text{def}} HC_*^h(M, \xi).$$

this is called the cylindrical contact homology of contact manifold (M, ξ) .

Prop: $\varphi: (M, \xi) \rightarrow (M', \xi')$ contactomorphism s.t. $\varphi_* h = h'$ for $h \in [S', M]$. Assume \exists contact 1-form α' of ξ' s.t. α' is h' -admissible, then \exists contact 1-form α of ξ s.t. α is h -admissible and $HC_*^h(M, \xi) = HC_*^{h'}(M', \xi')$.

$\Rightarrow HC_*^h(M, \xi)$ defines a contact invariant (of contact str)_{up to contactomorphism}.

One can use $HC_*^h(M, \xi)$ to distinguish different contact str.

Ex. $T^3 = S^1 \times S^1 \times S^1$, where $S^1 = \mathbb{R}/\mathbb{Z}$, in coordinate (p, φ, θ) .

Consider $\alpha_k := \cos(2\pi k p) d\theta + \sin(2\pi k p) dp$. $k \in \mathbb{N}_{\geq 1}$.

$$\begin{aligned} \text{Then } \alpha_k \wedge d\alpha_k &= (\cos(2\pi k p) d\theta + \sin(2\pi k p) dp) \wedge \\ &\quad 2\pi k p (-\sin(2\pi k p) dp \wedge d\theta + \cos(2\pi k p) dp \wedge dp) \\ &= 2\pi k p (-\sin^2(2\pi k p) dp \wedge dp \wedge d\theta + \\ &\quad \cos^2(2\pi k p) d\theta \wedge dp \wedge dp) \\ &= 2\pi k p dp \wedge dp \wedge d\theta = 0 \end{aligned}$$

Reeb vector field R_{α_k} is

$$R_{\alpha_k} = \sin(2\pi k p) \partial_p + \cos(2\pi k p) \partial_\theta$$

\Rightarrow closed Reeb orbits are in the form:

$$\{p\} \times \mathbb{T}^2 \simeq \{p\} \times \left[\begin{array}{c} \text{diagram of a square with diagonal lines and arrows} \end{array} \right]$$

$\left(\mathbb{T}^3 = \coprod_{p \in \mathbb{T}^2/2} \{p\} \times \mathbb{T}^2 \right)$

$\begin{array}{c} \uparrow \partial_\theta \\ \rightarrow \partial_p \end{array}$

In particular, all closed Reeb orbits are non-contractible.

Remark These orbits are degenerate (so extra work is needed).

Thm For $h = [t \rightarrow (0,0,t)]$, we have

$$HC_*^h(\mathbb{T}^3, \{k\}) = \begin{cases} \mathbb{Z}_2^k & * \text{ is odd} \\ \mathbb{Z}_2^k & * \text{ is even} \end{cases}$$

\Rightarrow For different k, l , $\mathfrak{f}_k \stackrel{\text{cont}}{\neq} \mathfrak{f}_l$.

(Here one needs to practice an Exercise: if $h, h' \in [S^1, \mathbb{T}^3]$, primitive and mapped to trivial class under projection $\mathbb{T}^3 \rightarrow S^1$, $(p, \varphi, \theta) \mapsto p$. Then \exists a contactomorphism $\varphi: (\mathbb{T}^3, \mathfrak{f}_k) \rightarrow \mathbb{T}^3$ s.t. $\varphi_* h = h'$.)

Remark Observe that for each $k \in \mathbb{N}_{\geq 1}$, consider smooth deformation,

$$\ker((1-s)\alpha_k + s dp) \quad s \in [0, 1] \quad \swarrow \text{not contact}$$

and we get from $\mathfrak{f}_k (= \ker \alpha_k)$ to $\ker(dp)$. So topologically all hypersurfaces \mathfrak{f}_k (for $k \in \mathbb{N}_{\geq 1}$) are the same.

(\Rightarrow we need refined contact geo machinery to distinguish $\mathfrak{f}_k, \mathfrak{f}_l$.)

Remark This result has been known since 90s (by Giroux, Kanda).